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The fantail operates on the error signal
 $w - T$, and as the fantail turns, it
drives the turret to turn. $x y \text{ Wind} * * qW$

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qT qF Fantail Turret = Wind angle =
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from a lead car: Throttle. Position of
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given by $A_1 A_2 A_3 Y(s) = + + s s \dots$

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~~Consider the system in Figure 2.79 where~~

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~~Gc(*) = 10, H(s...~~

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control system is the active control of the suspension system. One feedback control system uses a shock absorber consisting of a cylinder filled with a compressible fluid that provides both spring and Modern

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